

Listing Of The Claims

1. (Currently Amended) A hand truck comprising:
a first toe-portion having a first roller and a first weight sensor, wherein the first roller has an axle and a wheel disposed about the axle, and the first weight sensor is mounted to the axle;
a second toe-portion having a second roller and a second weight sensor;
a bulkhead connecting the first toe-portion and the second toe-portion, and having a third roller.
2. (Original) The hand truck of claim 1, further comprising a third weight sensor mounted to the bulkhead.
3. (Original) The hand truck of claim 2 further comprising a third weight sensor mounted to the third roller.
4. (Cancelled)
5. (Original) The hand truck of claim 1, wherein the third roller has an ~~axel~~ axle and a wheel disposed about the ~~axel~~ axle, and wherein the hand truck further comprises a third weight sensor mounted to the ~~axel~~ axle.
6. (Original) The hand truck of claim 1, further comprising a handle joined to the third roller, and the third roller is capable of swiveling in response to changes in a position of the handle.

7. (Original) The hand truck of claim 1, further comprising a microprocessor in communication with the weight sensors and capable of receiving a weight-sensor-signal from at least one of the weight sensors, the weight-sensor-signal corresponding to a weight sensed by the corresponding weight sensor.
8. (Original) The hand truck of claim 7, wherein the microprocessor is capable of determining a sum, the sum being determined by adding the weight sensed by the first weight sensor and the weight sensed by the second weight sensor.
9. (Original) The hand truck of claim 8, further comprising a display in communication with the microprocessor, and the microprocessor is further capable of providing a sum-signal to the display, and the display is capable of providing information corresponding to the sum-signal to a person.
10. (Original) The hand truck of claim 1, further comprising a display in communication with at least one of the weight sensors, the display being capable of receiving a weight-sensor-signal corresponding to a weight sensed by the at least one of the weight sensors, the weight-sensor-signal corresponding to the weight sensed by the at least one of the weight sensors, and the display is capable of providing information corresponding to the weight-sensor-signal.
11. (Currently Amended) A method of weighing, comprising:

providing a hand truck having a first toe-portion, a second toe-portion and a bulkhead connecting the first toe-portion and the second toe-portion, each toe-portion having a weight sensor mounted thereon, and wherein the first toe-portion includes a roller having an axle and a wheel disposed about the axle, and the first weight sensor is mounted to the axle;

placing an object on the hand truck;

receiving at least one weight-signal from at least one of the weight sensors;

displaying information corresponding to the weight signal.

12. (Currently Amended) The method of claim 11, wherein a weight-signal is received from all the weight sensors, and the displayed information is a number corresponding to a sum of weights indicated by the weight-signals.

13. (New) A hand truck comprising:

a first toe-portion having a first roller and a first weight sensor;

a second toe-portion having a second roller and a second weight sensor;

a bulkhead connecting the first toe-portion and the second toe-portion, the bulkhead having a third roller that includes an axle and a wheel disposed about the axle, and wherein the hand truck further comprises a third weight sensor mounted to the axle.

14. (New) The hand truck of claim 13, further comprising a third weight sensor mounted to the bulkhead.
15. (New) The hand truck of claim 14 further comprising a third weight sensor mounted to the third roller.
16. (New) The hand truck of claim 13, wherein the first roller has an axle and a wheel disposed about the axle, and the first weight sensor is mounted to the axle.
17. (New) The hand truck of claim 13, further comprising a handle joined to the third roller, and the third roller is capable of swiveling in response to changes in a position of the handle.
18. (New) The hand truck of claim 13, further comprising a microprocessor in communication with the weight sensors and capable of receiving a weight-sensor-signal from at least one of the weight sensors, the weight-sensor-signal corresponding to a weight sensed by the corresponding weight sensor.
19. (New) The hand truck of claim 18, wherein the microprocessor is capable of determining a sum, the sum being determined by adding the weight sensed by the first weight sensor and the weight sensed by the second weight sensor.

20. (New) The hand truck of claim 19, further comprising a display in communication with the microprocessor, and the microprocessor is further capable of providing a sum-signal to the display, and the display is capable of providing information corresponding to the sum-signal to a person.

21. (New) The hand truck of claim 13, further comprising a display in communication with at least one of the weight sensors, the display being capable of receiving a weight-sensor-signal corresponding to a weight sensed by the at least one of the weight sensors, the weight-sensor-signal corresponding to the weight sensed by the at least one of the weight sensors, and the display is capable of providing information corresponding to the weight-sensor-signal.

22. (New) A method of weighing, comprising:
providing a hand truck having a first toe-portion, a second toe-portion and a bulkhead connecting the first toe-portion and the second toe-portion, each toe-portion having a weight sensor mounted thereon, and wherein the bulkhead has a roller that includes an axle, a wheel disposed about the axle, and a third weight sensor mounted to the axle;
placing an object on the hand truck;
receiving at least one weight-signal from at least one of the weight sensors;
displaying information corresponding to the weight signal.

23. (New) The method of claim 22, wherein a weight-signal is

received from all the weight sensors, and the displayed information is a number corresponding to a sum of weights indicated by the weight-signals.